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## LINEAR REGRESSIONS, SHORTS TO LONG

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## LINEAR REGRESSIONS, SHORTS TO LONG ${ }^{1}$

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We study the identification problem of the linear long regression coefficients by data combination. Unlike the usual data combination problem, we consider combining multiple short regressions of the same outcome with different regressors. For this conceptually novel problem, we provide partial identification results for the long regression coefficients under a restriction on the unknown correlation structure. Specifically, we employ an elliptic constraint from the relations among the explained variations of the regressions to induce the bounds.

Keywords: Data combination, Linear regression, Elliptic constraint.

## 1. INTRODUCTION

Suppose that there are two studies on the same outcome $y$ sampled from the same population and each study sample contains different key variables $x_{1}$ and $x_{2}$ that are unavailable jointly. Namely, we obtain the summary statistics from two studies of ( $y, x_{1}$ ) and $\left(y, x_{2}\right)$ separately, but not of $\left(y, x_{1}, x_{2}\right)$. In this study, we consider the identification problem of the long regression $E\left[y \mid x_{1}, x_{2}\right]$ when the short regressions from two separate studies $E\left[y \mid x_{1}\right]$ and $E\left[y \mid x_{2}\right]$ are available.

This problem is similar to but different from the existing identification problem under data combination. Cross and Manski (2002) study nonparametric identification of the long regression $E\left[y \mid x_{1}, x_{2}\right]$ from the short conditional distributions $P\left[y \mid x_{1}\right]$ and $P\left[x_{1} \mid x_{2}\right]$. Ichimura and Martinez-Sanchis (2009) consider a semiparametric estimation problem of a related data combination problem. Molinari and Peski (2006) generalized the result of Cross and Manski (2002) for the infinitely supported $y$. Pacini (2019) further studies the relation in long linear projections and short linear projections. We focus on a different problem of different short regressions of $E\left[y \mid x_{1}\right]$ and $E\left[y \mid x_{2}\right]$. Such a problem appears in a frequent context but little has been done in the literature.

This identification problem appears frequently as an empirical challenge. For example, a study of $y$ on $x_{2}$ suggests that $x_{2}$ is a key confounder for the causal relation between

[^0]$y$ and $x_{1}$. However, the confounder $\left(x_{2}\right)$ is unobserved in the study sample of $y$ on $x_{1}$. This unobserved variable $\left(x_{2}\right)$ may also be a candidate for the mediation analysis in the relation between $y$ and $x_{1}$. For the example below, we illustrate the problem of combining two short regressions that suffer from the omitted variable bias.

EXAMPLE 1.1 Suppose that one is interested in the impact of the years of schooling $\left(x_{0}\right)$ on the earnings $(y)$. The leading concern is the ability bias: the unobserved ability is correlated with both education level and earnings. Certain survey data contain a usually unavailable confounding variable such as the IQ test score $\left(x_{1}\right)$; however, another key confounder of the birth location $\left(x_{2}\right)$ may be limited because of confidentiality reasons. Nevertheless, the geographical information ( $x_{2}$ ) with the earnings data ( $y$ ) may be publicly available in a different data source. One may run two separate regressions of earnings $(y)$ on schooling $\left(x_{0}\right)$ and IQ score $\left(x_{1}\right)$, and earnings $(y)$ on schooling $\left(x_{0}\right)$ and a location variable ( $x_{2}$ ). Both regressions suffer from omitted variable biases; hence, we aim to recover the coefficient on $x_{0}$ in the long-regression of earnings $(y)$ on schooling $\left(x_{0}\right)$, and both IQ score $\left(x_{1}\right)$ as well as the location variable $\left(x_{2}\right)$.

Objectives in these examples require the coefficients of the long regression $E\left[y \mid x_{1}, x_{2}\right]$; however, only the short regressions $E\left[y \mid x_{1}\right]$ and $E\left[y \mid x_{2}\right]$ may be available.

In this study, we propose partial identification strategies for the linear long regression coefficients. First, we consider the case when all the variables in the long regression appear in some of the study samples. If the correlation structure of $x_{1}$ and $x_{2}$ is known, then the short regression coefficients point identify the long regression coefficients. If the correlation structure is unknown, then the target parameter is only partially identified. We consider the bounds as a tool for the sensitivity analysis of the target parameter in the worst-case correlation coefficients.

Second, we consider an additional omitted variable that is never observed in any studies. In Example 1.1 above, we consider the IQ test score as a proxy for the unobserved ability. However, the residual ability net of the IQ score may still plague the identification. With such an omitted variable that is never observed, the target parameter is not point identified from the known correlation structure. Nevertheless, we show that the elliptic constraint on the explained variation of the long regression induces the bounds
that are the intersection of bounds from each study. The use of the elliptic constraint is related to the seminal work of Leamer (1978) and its followers. This use of the elliptic constraint is conceptually new in the literature of data combination.

We also contribute to the literature of sensitivity analysis against omitted variables. The sensitivity of regression estimates are studied in a wide range of literature including Mauro (1990), Murphy and Topel (1990), Frank (2000), Imbens (2003), Altonji et al. (2005), Clarke (2009), Bellows and Miguel (2006), Hosman et al. (2010), González and Miguel (2015), Krauth (2016), Cinelli and Hazlett (2020). Recently, Masten and Poirier (2022) study the sensitivity measure proposed by Oster (2019) that follows the idea of Altonji et al. (2005) and show that the sign of the coefficient of interest is sensitive to the measure when the omitted variable is relatively unimportant than the observed control variables. Diegert et al. (2022) also consider the sensitivity analysis without assuming that control variables are exogenous. Those recent studies approach the omitted variable problem for a particular variable of interest in the long regression in a single study. We approach this problem from a different perspective of combining multiple short regressions. Specifically, we demonstrate that the combining multiple short regressions tighten the bounds for the long regression with omitted variables.

In the remainder of this paper, we present the identification result in Section 2. In Section 3, we introduce an omitted variable that is never observed in either of the two studies. In Section 4, we conclude the paper with discussion of future challenges.

## 2. IDENTIFYING LINEAR LONG REGRESSION FROM SHORT REGRESSIONS

Consider there are two studies $s \in\{1,2\} \equiv \mathcal{S}$ on each study sample drawn from a single population. For example, the two studies may contain key omitted variables separately, the determinants of a treatment assignment separately, or a treatment variable and a mediating variable separately. Two studies share the same outcome of interest $y \in \mathbb{R}$, the ideal vector of $L$ explanatory variables $z \in \mathcal{R}^{L}$ and a linear conditional expectation function (CEF) of $y$ given $z, E[y \mid z]=z^{\prime} \beta$. However, the whole vector $z$ is never observed in each study. Alternatively, for each study $s$, we observe a sample of $\left(y, z_{s}\right)$ where $z_{s}=\left[x_{0}^{\prime}, x_{s}^{\prime}\right]^{\prime}$ is a subvector of $z$ such that $x_{0}$ is common across studies but $x_{s}$ is study specific. By construction, we have $x_{1} \cap x_{2}=\emptyset$ and $z=\left[x_{0}^{\prime}, x_{1}^{\prime}, x_{2}^{\prime}\right]^{\prime}$. Our
target parameter is $c^{\prime} \beta$ for some non-zero vector $c \in \mathbb{R}^{L}$; namely, we aim to recover some of the long-regression coefficients when only the short-regression coefficients are available.

Such an evidence aggregation problem arises when a researcher ex-post realizes the use of two different study samples jointly. Consequently, the researcher may have assess only through the summary statistics from published studies, confidential administrative, or proprietary data. Hence, we limit the information available to the analyst to be the following: the short projection coefficients $\mathcal{L}\left(y \mid z_{s}\right)=z_{s}^{\prime} \gamma_{s}, s \in \mathcal{S}$; the variance-covariance matrices of $z_{s}, \Sigma_{s, s^{\prime}} \equiv E\left(z_{s} z_{s^{\prime}}\right)$ for $\left\{s, s^{\prime}\right\} \in \mathcal{S}$; the residual variance of linear projection $\eta^{2}\left(z_{s}\right) \equiv \operatorname{Var}\left(y-\mathcal{L}\left(y \mid z_{s}\right)\right)$ for $s \in \mathcal{S}$; and the variance of $y, \operatorname{Var}(y)$. Let $L_{s}<L$ be the length of $x_{s}$ for each $s \in\{0,1,2\}$.

In addition to the Example 1.1 in Introduction, we illustrate the motivation further in the following two examples:

Example 2.1 Consider a hypothetical policy $\left(x_{1,1}\right)$ offering tuition waivers for eligible students. Suppose the eligibility $\left(x_{1,1}\right)$ is purely determined by the field of study $\left(x_{1,2}\right)$ and parental income $\left(x_{2}\right)$. One study collects a representative sample of schools and their students about their eligibility $\left(x_{1,1}\right)$, their field of study $\left(x_{1,2}\right)$ and earnings after graduation $(y)$, but missing their parental income $\left(x_{2}\right)$. Eligible students tend to be from households with lower parental income and parental income is a critical confounder for the regression of policy and field of study $x_{1}=\left\{x_{1,1}, x_{1,2}\right\}$ on $y$. Suppose that another study collects another representative sample of households about their household income ( $x_{2}$ ) and college graduates' earnings ( $y$ ), but the eligibility of the program is unknown because their field of study is unknown. We aim to recover the coefficient on $x_{1,1}$ in the long-regression of earnings $(y)$ on the policy eligibility ( $x_{1,1}$ ), controlling for both students' field of study $\left(x_{1,2}\right)$ and households income $\left(x_{2}\right)$.

Example 2.2 Consider a randomized evaluation of a policy $x_{1}$ on an outcome $y$. A referee suggests that another background information $x_{2}$ may be the mechanism that drives the policy impact of $x_{1}$ on $y$. Unfortunately, such information $x_{2}$ is not available in the study at hand. Nevertheless, administrative data on the same study area contains both $y$ and $x_{2}$, but not $x_{1}$ which is the intervention introduced by the researcher. We
aim to recover the coefficient on $x_{1}$ after controlling for $x_{2}$ to compare the coefficient on $x_{1}$ without controlling for $x_{2}$.

We first consider identification of $c^{\prime} \beta$ pretending that $E\left(x_{1} x_{2}^{\prime}\right)$ is known. In other words, the whole variance matrix $W \equiv E\left[z z^{\prime}\right]$ is known.

For every $s \in \mathcal{S}$, the vector of linear projection coefficients of $y$ onto $z_{s}$,

$$
\gamma_{s}=E\left[z_{s} z_{s}^{\prime}\right]^{-1} E\left[z_{s} y\right]=E\left[z_{s} z_{s}^{\prime}\right]^{-1} E\left[z_{s} z^{\prime}\right] \beta
$$

is identified. Consequently, we obtain $L_{s}$ number of linear constraints for $\beta \in \mathbb{R}^{L}$ for each $s \in \mathcal{S}$,

$$
\begin{equation*}
E\left(z_{s} z^{\prime}\right) \beta=E\left(z_{s} z_{s}^{\prime}\right) \gamma_{s} \tag{2.1}
\end{equation*}
$$

because $\gamma_{s}$ is the vector of linear projection coefficients of $z_{s}$, and the CEF is linear. If the whole vector of covariates $z$ is observed somewhere in the studies, then the linear constraints (2.1) are sufficient for identification.

Proposition 2.1 If $z_{1} \cup z_{2}=z$ and $W=E\left[z z^{\prime}\right]$ is a known positive-definite matrix, then $\beta$ is point-identified.

Proof: By stacking the matrices of (2.1) over studies, we have

$$
\left[\begin{array}{l}
E\left[x_{0} z^{\prime}\right] \\
E\left[x_{1} z^{\prime}\right] \\
E\left[x_{0} z^{\prime}\right] \\
E\left[x_{2} z^{\prime}\right]
\end{array}\right] \beta=\left[\begin{array}{l}
E\left[x_{0} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{1} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{0} z_{2}^{\prime}\right] \gamma_{2} \\
E\left[x_{2} z_{2}^{\prime}\right] \gamma_{2}
\end{array}\right]
$$

Let

$$
J=\left[\begin{array}{cccc}
I_{L_{0}} & O_{L_{1}} & O_{L_{0}} & O_{L_{2}} \\
O_{L_{0}} & I_{L_{1}} & O_{L_{0}} & O_{L_{2}} \\
O_{L_{0}} & O_{L_{1}} & O_{L_{0}} & I_{L_{2}}
\end{array}\right]
$$

where $I_{k}$ is $k \times k$ identity matrix and $O_{k}$ is $k \times k$ zero matrix. Multiplying $J$ from left, we obtain

$$
J\left[\begin{array}{l}
E\left[x_{0} z^{\prime}\right] \\
E\left[x_{1} z^{\prime}\right] \\
E\left[x_{0} z^{\prime}\right] \\
E\left[x_{2} z^{\prime}\right]
\end{array}\right] \beta=E\left[z z^{\prime}\right] \beta=J\left[\begin{array}{l}
E\left[x_{0} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{1} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{0} z_{2}^{\prime}\right] \gamma_{2} \\
E\left[x_{2} z_{2}^{\prime}\right] \gamma_{2}
\end{array}\right] .
$$

Hence

$$
\beta=W^{-1} J\left[\begin{array}{l}
E\left[x_{0} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{1} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{0} z_{2}^{\prime}\right] \gamma_{2} \\
E\left[x_{2} z_{2}^{\prime}\right] \gamma_{2}
\end{array}\right] .
$$

REmark 2.1 The choice of $J$ matrix is not unique and $\beta$ is over-identified. For example, taking

$$
\tilde{J}=\left[\begin{array}{cccc}
O_{L_{0}} & O_{L_{1}} & I_{L_{0}} & O_{L_{2}} \\
O_{L_{0}} & I_{L_{1}} & O_{L_{0}} & O_{L_{2}} \\
O_{L_{0}} & O_{L_{1}} & O_{L_{0}} & I_{L_{2}}
\end{array}\right]
$$

obtains another identification formula of

$$
\beta=W^{-1} \tilde{J}\left[\begin{array}{l}
E\left[x_{0} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{1} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{0} z_{2}^{\prime}\right] \gamma_{2} \\
E\left[x_{2} z_{2}^{\prime}\right] \gamma_{2}
\end{array}\right] .
$$

Hence, the underlying model has a testable restriction.

The above proposition assumes the knowledge of $W$ but the cross moment between $x_{1}$ and $x_{2}$ is usually unknown because $x_{1}$ and $x_{2}$ are not observed for the same unit.

When the covariance of $x_{1}$ and $x_{2}$ are unknown, $c^{\prime} \beta$ becomes a set-identified object. Let

$$
b \equiv J\left[\begin{array}{l}
E\left[x_{0} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{1} z_{1}^{\prime}\right] \gamma_{1} \\
E\left[x_{0} z_{2}^{\prime}\right] \gamma_{2} \\
E\left[x_{2} z_{2}^{\prime}\right] \gamma_{2}
\end{array}\right] .
$$

Specifically, the upper and lower bounds for $c^{\prime} \beta$ is attained from the maximum and minimum of the following objective function:

$$
c^{\prime} W^{-1} b
$$

subject to

$$
W=\left[\begin{array}{ccc}
\tilde{A} & B & C \\
B^{\prime} & R_{11} & R_{12} \\
C^{\prime} & R_{12}^{\prime} & R_{22}
\end{array}\right]
$$

where $\tilde{A}=E\left[x_{1} x_{1}^{\prime}\right], R_{11}=E\left[x_{0} x_{0}^{\prime}\right], R_{12}=E\left[x_{0} x_{2}^{\prime}\right], R_{22}=E\left[x_{2} x_{2}^{\prime}\right], B=E\left[x_{0} x_{1}^{\prime}\right]$ and $C=E\left[x_{1} x_{2}^{\prime}\right]$ and $C$ is the only unknown matrix, $c, b \neq 0$ are known vector of length $L$. Note that

$$
(c-b)^{\prime} W^{-1}(c-b)=c^{\prime} W^{-1} c+b^{\prime} W^{-1} b-b^{\prime} W^{-1} c-c^{\prime} W^{-1} b
$$

and hence

$$
c^{\prime} W^{-1} b=\left[(c-b)^{\prime} W^{-1}(c-b)-\left(c^{\prime} W^{-1} c+b^{\prime} W^{-1} b\right)\right] / 2 .
$$

As in the following lemma, $c^{\prime} W^{-1} c$ is a convex function with respect to $C$.

Lemma 2.1 For any non-zero vector $a$ and a positive definite matrix

$$
W=\left[\begin{array}{ccc}
\tilde{A} & B & C \\
B^{\prime} & R_{11} & R_{12} \\
C^{\prime} & R_{12}^{\prime} & R_{22}
\end{array}\right],
$$

$a^{\prime} W^{-1} a$ is a convex function with respect to $C$.

Proof: Proof is in the Appendix.
Consequently, $(c-b)^{\prime} W^{-1}(c-b), c^{\prime} W^{-1} c$ and $b^{\prime} W^{-1} b$ are convex function of $C$, the objective function is difference in convex functions. Consequently, the objective function is not necessarily convex.

For an illustrative example, consider a scalar $x_{1}$ and $x_{2}$ case with empty $x_{0}$. Let

$$
W=\left[\begin{array}{cc}
\sigma_{1}^{2} & \rho \sigma_{1} \sigma_{2} \\
\rho \sigma_{1} \sigma_{2} & \sigma_{2}^{2}
\end{array}\right]
$$

where $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ are the variances of $x_{1}$ and $x_{2}$, and $\rho$ is the correlation coefficient, which is the only unknown parameter. Figure 2.1 illustrate the objective function as a function of $\rho$ in three different signs of $\beta=\left(\beta_{0}, \beta_{1}, \beta_{2}\right)$. As shown in the figure, the objective function can be either concave (Panel A), convex (Panel B), or non-convex (Panel C) in the value of $\rho$. An important remark of the illustration is that the objective function can have an informative upper or lower bound without restricting the unknown correlation coefficient $\rho$. Nevertheless, such an informative bound is not available in general.

As demonstrated in Figure 2.1, the objective function is not necessarily bounded. If $\rho$ is not bounded, then the objective function $c^{\prime} W^{-1} b$ is not necessarily bounded as $W$ becomes singular when $\rho=1$. As a result, the bounds are not informative without restricting $W$. Hence, we may use $\rho$ as the sensitivity parameter to assess the sensitivity of the bounds against unknown correlation structure of two separate dataset.

In the earlier examples, we often have a particular few covariates that are relevant and not in common across two studies. If the number of non-common covariates is small, the non-convex optimization is straightforward with a brute-force search. For a larger


Figure 2.1.- Plot of the objective function value as the function of $\rho$ in illustrative numerical examples of different specifications over $-0.95 \leq \rho \leq 0.95$. All specifications are common in the distribution of covariates and the intercept $\beta_{0}=0.1$.
dimensional problem, we may resort to an optimization algorithm for a non-convex optimization. In particular, the objective function is a difference in convex functions and a DC (Difference of Convex functions) algorithm (Le Thi and Pham Dinh, 2018, for example) may be applicable.

## 3. ROBUSTNESS AGAINST COMMON OMITTED VARIABLES

In the aforementioned examples, all the relevant variables are observed somewhere in the study samples. Nevertheless, we may concern about omitted variables that are never observed in any of the study samples. For example, in Example 1.1, IQ score is not a perfect proxy of the unobserved ability and the residual ability net of the IQ score may still cause the omitted variable bias. The eligibility in Example 2.1 may be determined by an additional unobserved variable. In Example 2.2, $x_{1}$ is randomized, but $x_{2}$ may be correlated with an unobserved confounder.

An important example is the interaction term $x_{1} x_{2}$ which is the unobserved omitted variable. For the purpose of mediation analysis, the interaction term plays a critical role in decomposing the direct and indirect effect of the randomized policy $x_{1}$, and the interaction term is not observed in any of the study samples.

Hence, we consider a vector of omitted variables from both studies. Now, the vector of $L$ explanatory variables $z$ is composed of the vector that is observed in some study and the other vector of the omitted variables $w$ such that $z=\left[x_{0}^{\prime}, x_{1}^{\prime}, x_{2}^{\prime}, w^{\prime}\right]^{\prime}$. Each study has its own vector of omitted variables $w_{1}=\left[x_{2}^{\prime}, w^{\prime}\right]^{\prime}$ and $w_{2}=\left[x_{1}^{\prime}, w^{\prime}\right]^{\prime}$.

With omitted variables $w$, the above point identification does not hold. Nevertheless,
in addition to the linear constraints (2.1), there is a set of quadratic constraints for the variance of $y$ in each study. For $\sigma_{y}^{2}=\operatorname{Var}(y)$, we have

$$
\begin{equation*}
\gamma_{s}^{\prime} E\left(z_{s} z_{s}^{\prime}\right) \gamma_{s} \leq \beta^{\prime} E\left(z z^{\prime}\right) \beta \leq \sigma_{y}^{2} \tag{3.1}
\end{equation*}
$$

Below, we exploit both equations (2.1) and (3.1) given the knowledge about $\gamma_{s}$ and $E\left(x_{s} x_{s}^{\prime}\right)$. The unknown objects are $\beta, E\left(x_{s} w_{s}^{\prime}\right)$ and $E\left(w_{s} w_{s}^{\prime}\right)$. We consider constructing the bounds for the parameter of interest $\theta=c^{\prime} \beta$ given the knowledge of $E\left(z_{s} w_{s}^{\prime}\right)$ and $E\left(w_{s} w_{s}^{\prime}\right)$ that are partially identified. Later, we aggregate the bounds for $c^{\prime} \beta$ by intersecting them across $s=1$ and $s=2$. In the last step, we construct the bounds of $c^{\prime} \beta$ by incorporating partial identification of $E\left(x_{s} w_{s}^{\prime}\right)$ and $E\left(w_{s} w_{s}^{\prime}\right)$.

The upper and lower bounds for $\theta$ are obtained by optimizing $c^{\prime} \beta$ subject to (2.1) and (3.1). This optimization can be viewed as a series of linear optimizations with linear and quadratic constraints of the following form: for each $s \in\{1,2\}$,

$$
\begin{equation*}
\max / \min _{\beta \in \mathbb{R}^{L}} c^{\prime} \beta \tag{3.2}
\end{equation*}
$$

s.t. $E\left(x_{s} z^{\prime}\right) \beta=E\left(z_{s} z_{s}^{\prime}\right) \gamma_{s}$,

$$
\gamma_{s}^{\prime} E\left(z_{s} z_{s}^{\prime}\right) \gamma_{s} \leq \beta^{\prime} W \beta \leq \sigma_{y}^{2} .
$$

We illustrate the constraints in an illustration of scalar $x_{1}, x_{2}$ and $w$. Figure 3.2 illustrate the constraints as a cross section view along with the coefficient of $x_{2}$ that satisfies the linear constraint (2.1). As illustrated in the figure, we can ignore the lower bound of the quadratic inequality constraint because the optimum is attained when the upper bound of the elliptic inequality is binding.


Figure 3.2.- A numerical illustration of two observed variables with coefficients $\left(\beta_{1}, \beta_{2}\right)$ and an omitted variable with a coefficient $\beta_{3}$. The figure represents the twodimensional $\left(\beta_{1}, \beta_{2}\right)$ plot of the cross section view of the three dimensional space $\left(\beta_{1}, \beta_{2}, \beta_{3}\right)$ along the linear constraint that is solved for $\beta_{2}$. Given $c$ (black arrows), the maximum and minimum of $c^{\prime} \beta$ (red dots) are the intersections of the linear constraint (blue straight line) and the upper bound of the quadratic constraint (the outside orange ellipse). The identified set (bold orange line) is the interval between the red dots.

This problem (3.2) is abstracted into the following canonical form

$$
\begin{equation*}
\max / \min _{\beta \in \mathbb{R}^{L}} c^{\prime} \beta, \tag{3.3}
\end{equation*}
$$

s.t. $A \beta=b$,

$$
\ell \leq \beta^{\prime} W \beta \leq u
$$

where $A$ is a $(\bar{L}, L)$ matrix, $b$ is a vector of length $\bar{L}$ and $W$ is a symmetric and positive semidefinite $(L, L)$ matrix. The problem (3.3) has a closed-form solution as in the next
lemma.

Lemma 3.1 Given $W$, the solutions to the optimization problem with respect to $\beta$ in the canonical form (3.3) are given by

$$
\begin{equation*}
\beta=W^{-1} A^{\prime}\left(A W^{-1} A^{\prime}\right)^{-1} b-\mu\left(W^{-1}-H\right) c \tag{3.4}
\end{equation*}
$$

where

$$
\begin{align*}
\mu & = \pm \sqrt{\frac{u-b^{\prime}\left(A W^{-1} A^{\prime}\right)^{-1} b}{c^{\prime}\left(W^{-1}-H\right) c}}  \tag{3.5}\\
H & =W^{-1} A^{\prime}\left(A W^{-1} A^{\prime}\right)^{-1} A W^{-1} \tag{3.6}
\end{align*}
$$

Proof: Noting that at the optimum the upper bound of the quadratic inequality constraint is binding, while the lower bound is not, we form the Lagrangean as

$$
\begin{equation*}
\mathcal{L}=c^{\prime} \beta-\lambda^{\prime}(A \beta-b)-\frac{1}{2 \mu}\left(u-\beta^{\prime} W \beta\right) \tag{3.7}
\end{equation*}
$$

where $(\lambda, 1 / 2 \mu) \in \mathbb{R}^{\bar{L}+1}$ are Lagrange multipliers. The first-order conditions in $\beta$ give

$$
\begin{equation*}
\beta=\mu W^{-1}\left(A^{\prime} \lambda-c\right) . \tag{3.8}
\end{equation*}
$$

The constraint $A \beta=b$ implies

$$
\begin{equation*}
\lambda=\left(A W^{-1} A^{\prime}\right)\left(A W^{-1} c+\frac{1}{\mu} b\right) . \tag{3.9}
\end{equation*}
$$

Combining (3.8) and (3.9) yields $\beta$ in the lemma. To pin down $\mu$, we plug in (3.8) and (3.9) into $\beta^{\prime} W \beta=u$. It leads to (3.5).

To apply the lemma, for each $A$, observe that $A W^{-1}$ can be seen as the coefficient matrix of the linear projections of $x_{s}$ onto $z$, which is, for each $s \in\{0, \mathcal{S}\}$,

$$
A W^{-1}=\left(\begin{array}{ll}
I_{L_{s} \times L_{s}} & O_{L_{s} \times\left(L-L_{s}\right)} \tag{3.10}
\end{array}\right) .
$$

Hence, we have

$$
\begin{align*}
A W^{-1} A^{\prime} & =E\left(x_{s} x_{s}^{\prime}\right)  \tag{3.11}\\
H & =\left(\begin{array}{cc}
E\left(x_{s} x_{s}^{\prime}\right)^{-1} & O_{L_{s} \times\left(L-L_{s}\right)} \\
O_{\left(L-L_{s}\right) \times L_{s}} & O_{\left(L-L_{s}\right) \times\left(L-L_{s}\right)}
\end{array}\right) . \tag{3.12}
\end{align*}
$$

Consider the linear projection of $w_{s}$ onto $x_{s}$,

$$
\begin{equation*}
w_{s}=\Pi^{s} x_{s}+v_{s} \tag{3.13}
\end{equation*}
$$

where $\Pi^{s}=E\left(w^{s} x_{s}^{\prime}\right) E\left(x_{s} x_{s}^{\prime}\right)^{-1}$. Then, by the inverse formula for a block matrix,

$$
W^{-1}=\left(\begin{array}{cc}
E\left(x_{s} x_{s}^{\prime}\right)^{-1}+\Pi^{s \prime} E\left(v_{s} v_{s} \prime\right)^{-1} \Pi^{s} & -\Pi^{s \prime} E\left(v_{s} v_{s}^{\prime}\right)^{-1}  \tag{3.14}\\
-E\left(v_{s} v_{s}^{\prime}\right)^{-1} \Pi^{s} & E\left(v_{s} v_{s}^{\prime}\right)^{-1}
\end{array}\right)
$$

Hence, we obtain

$$
\begin{align*}
W^{-1}-H & =\left(\begin{array}{cc}
\Pi^{s \prime} E\left(v_{s} v_{s}^{\prime}\right)^{-1} \Pi^{s} & -\Pi^{s \prime} E\left(v_{s} v_{s}^{\prime}\right)^{-1} \\
-E\left(v_{s} v_{s}^{\prime}\right)^{-1} \Pi^{s} & E\left(v_{s} v_{s}^{\prime}\right)^{-1}
\end{array}\right)  \tag{3.15}\\
& =\binom{\Pi^{s \prime}}{I_{\left(L-L_{s}\right) \times\left(L-L_{s}\right)}} E\left(v_{s} v_{s}^{\prime}\right)^{-1}\left(\begin{array}{ll}
\Pi^{s} & \left.I_{\left(L-L_{s}\right) \times\left(L-L_{s}\right)}\right)
\end{array}\right.
\end{align*}
$$

Putting altogether, Lemma 3.1 gives the following proposition:

Proposition 3.1 Suppose that $W=E\left(z z^{\prime}\right)$ is constrained in an identified set $I S_{z z^{\prime}}$, then the identified set for $\theta=c^{\prime} \beta$ is the convex interval $\left[\max _{s} \theta_{\ell}^{s}, \min _{s} \theta_{u}^{s}\right]$ where

$$
\begin{align*}
& \theta_{\ell}^{s}=c_{s}^{\prime} \gamma_{s}-\eta\left(z_{s}\right) \sqrt{\max _{W \in I S_{z z^{\prime}}} c^{\prime}\left(W^{-1}-H\right) c},  \tag{3.16}\\
& \theta_{u}^{s}=c_{s}^{\prime} \gamma_{s}+\eta\left(z_{s}\right) \sqrt{\max _{W \in I S_{z z^{\prime}}} c^{\prime}\left(W^{-1}-H\right) c} \tag{3.17}
\end{align*}
$$

where $W^{-1}-H$ is as shown in (3.15) and $c_{s}$ is the subvector of $c$ corresponding to the elements of $x_{s}$ in $z$,

Proof: The first terms in the right-hand sides of (3.16) and (3.17) follow by combining $b=E\left(x_{s} z^{\prime}\right) \gamma_{s},(3.10)$, and (3.11). Note also that the numerator in (3.5) equals to $\eta\left(z_{s}\right)=\sqrt{\operatorname{Var}\left(y-L\left(y \mid x_{s}\right)\right)}$, which is an identified quantity in study $s$. From the bounds for each $s$, we attain the stated bounds because

$$
\begin{aligned}
& \max _{W \in I S_{z z^{\prime}}} \min _{s} \theta_{u}^{s} \\
& \quad=\max _{W \in I S_{z z^{\prime}}} \min _{s}\left(c_{s}^{\prime} \gamma_{s}+\eta\left(z_{s}\right) \sqrt{c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right) \\
& \quad=\min _{s} \max _{W \in I S_{z z^{\prime}}}\left(c_{s}^{\prime} \gamma_{s}+\eta\left(z_{s}\right) \sqrt{c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right) \\
& \quad=\min _{s}\left(c_{s}^{\prime} \gamma_{s}+\eta\left(z_{s}\right) \sqrt{\max _{c^{\prime} W^{-1} c: W \in I S_{z z^{\prime}}} c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right)
\end{aligned}
$$

from $\eta\left(z_{s}\right) \geq 0$ for every $s$, and because

$$
\begin{aligned}
\min _{W \in I S_{z z z^{\prime}}} & \max _{s} \theta_{l}^{s} \\
& =\min _{W \in I S_{z z^{\prime}}} \max _{s}\left(c_{s}^{\prime} \gamma_{s}-\eta\left(z_{s}\right) \sqrt{c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right) \\
& =\max _{s} \min _{W \in I S_{z z^{\prime}}}\left(c_{s}^{\prime} \gamma_{s}-\eta\left(z_{s}\right) \sqrt{c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right) \\
& =\max _{s}\left(c_{s}^{\prime} \gamma_{s}-\eta\left(z_{s}\right) \sqrt{\max _{W \in I S_{z z^{\prime}}} c^{\prime} W^{-1} c-c^{\prime} H^{s} c}\right) .
\end{aligned}
$$

Q.E.D.

### 3.1. Implementation of the bounds

The above bounds $\left[\max _{s} \theta_{l}^{s}, \min _{s} \theta_{u}^{s}\right.$ ] for $c^{\prime} \beta$ are subject to the identified set of the unknown matrix $W$. As shown in Proposition 3.1, we need to obtain the maximum value of $c^{\prime} W^{-1} c$.

Below, we consider a scalar common omitted variable $w$. Note that the scalar unobservable can be a general structure given the additive model of the conditional expec-
tation function. Its variance matrix is

$$
W=\left[\begin{array}{cccc}
\tilde{A} & B & C & D_{1} \\
B^{\prime} & R_{11} & R_{12} & D_{2} \\
C^{\prime} & R_{12}^{\prime} & R_{22} & D_{3} \\
D_{1}^{\prime} & D_{2}^{\prime} & D_{3}^{\prime} & \tilde{r}
\end{array}\right]
$$

and the matrix $C$, the vector $D=\left[D_{1}, D_{2}, D_{3}\right]$, and a scalar $\tilde{r}$ are the unknown parameters. We consider a sequential optimization of the objective function $c^{\prime} W c$. In particular, we fix $C$ in the the upper-block submatrix

$$
\bar{A} \equiv\left[\begin{array}{ccc}
\tilde{A} & B & C \\
B^{\prime} & R_{11} & R_{12} \\
C^{\prime} & R_{12}^{\prime} & R_{22}
\end{array}\right]
$$

and maximizing

$$
c^{\prime}\left[\begin{array}{cc}
\bar{A} & D \\
D^{\prime} & \tilde{r}
\end{array}\right]^{-1} c
$$

over $D$ and $\tilde{r}$, and search for the maximizing $C$ by a brute-force search as in the case of no omitted variable.

Given the submatrix $\bar{A}, c^{\prime} W^{-1} c$ is a convex function with respect to the elements that correspond $D$ and $\tilde{r}$ as we show in the upcoming lemma below. Finding the maximum of a convex function over a convex constraint is known to have its solutions on the boundary of the constraint (Kubo et al., 2012, Chapter 12, for example). Hence, the optimization is nonetheless infeasible for a large number of the omitted variables because we need to list all the vertex of the convex constraints. Conversely, the sequential optimization is feasible when the first stage optimization is feasible.

Note that if $\bar{A}$ and the whole matrix $W$ are non-singular and $\tilde{r}>0$, we have

$$
W^{-1}=\left[\begin{array}{cc}
\bar{A}^{-1}+\bar{A}^{-1} D D^{\prime} \bar{A}^{-1} / k & -\bar{A}^{-1} D / k \\
-D^{\prime} \bar{A}^{-1} / k & 1 / k
\end{array}\right] .
$$

where $k \equiv \tilde{r}-D^{\prime} \bar{A}^{-1} D$. Since $\bar{A}$ is known, our objective is to find $D$ and $k$ that maximizes $c^{\prime} W^{-1} c$. We parameterize the objective function by $\tilde{y} \equiv\left[d^{\prime}, k\right]^{\prime}$ where $d=$ $\left[d_{11}, d_{12}, \ldots, d_{1 L_{2}}, d_{21}, d_{22}, \ldots, d_{L_{1} L_{2}}\right]^{\prime}$ so that

$$
D(d)=\left[d_{i j}\right]_{1 \leq i \leq L_{1}, 1 \leq j \leq L_{2}}
$$

as

$$
h(\tilde{y})=c^{\prime}\left[\begin{array}{cc}
A^{-1}+A^{-1} D D^{\prime} A^{-1} / k & -A^{-1} D / k \\
-D^{\prime} A^{-1} / k & 1 / k
\end{array}\right] c .
$$

This function $h$ is a weakly convex function.

Lemma 3.2 The Hessian matrix of $h(\tilde{y})$ is positive semi-definite.

Note again that the convexity of the objective function implies that the optimization problem is the minimization of a concave function. Since the constraint set is convex, a solution exists on the boundary of the constraint set.

Hence, we propose a nested-loop optimization: We fix the correlation structure among the observed non-common covariates and find $\tilde{y}$ that maximizes the objective function value, and iterate over the restrictions on the correlation structure.

The inner loop optimization involves optimization over the boundary of the constraints. If all the constraints are linear, then an optimal solution exists at one of vertices of a polyhedron generated from the linear constraints. However, the set of feasible $D$ and $k$ is constrained by the elliptic constraint of $k=\tilde{R}-D^{\prime} \tilde{A}^{-1} D$. Hence, we may approximate the elliptic constraint with a polyhedron (Ben-Tal and Nemirovski, 2001).

Below, we illustrate the optimization procedure when there is a scalar omitted variable $w$. To obtain an informative bound, one needs to specify three quantities: $\operatorname{Var}(w)$, $\operatorname{Corr}\left(x_{1}, x_{2}\right)$ and $\operatorname{Corr}\left(x^{\prime}, w\right)$ where $x=\left[x_{0}, x_{1}, x_{2}\right]^{\prime}$. Consider that one has the upper bound of $\operatorname{Var}(w) \leq \bar{\sigma}_{w}^{2}$ and worst-case correlation $\bar{\rho}$ such that the absolute values of $\operatorname{Corr}\left(x_{1}, x_{2}\right)$ and $\operatorname{Corr}(x, w)$ fall below $\bar{\rho}$.

If one consider a specific omitted variable $w$, then one may have its summary statistics
from other data sources that do not contain neither $y$ nor $\left(x_{1}, x_{2}\right)$. The variance bound for $V(w)$ may be constructed from the support of $w$ when $w$ is discrete. For example, if the omitted variable $w$ is the cross term $x_{1} x_{2}$ and both $x_{1}$ and $x_{2}$ are binary, then the correlation of $x_{1}$ and $x_{2}$ through the cross moment $E\left[x_{1} x_{2}\right]$ characterizes the unknown part of the variance matrix.

Note that normalization $\operatorname{Var}(w)=1$ as in Masten and Poirier (2022) is possible and the objective function is convex in the remaining unobserved vector $D$ from a similar argument as in Lemma 2.1. Given $\bar{\sigma}_{w}^{2}$, one may consider the sensitivity analysis with respect to the value of $\bar{\rho}$.

Note that given $C$ of the covariance of $x_{1}$ and $x_{2}$, the unknown parameters are $D$ of the covariance of $x$ and $w$ and a scalar $k=\sqrt{\operatorname{Var}(w)-D^{\prime} \tilde{A} D}$. Hence, the restrictions on $\{D, k\}$ is characterized by the following set of constraints: for each $x^{i} \in x$ and the corresponding correlation $d_{i}$ of $\operatorname{Corr}\left(x^{i}, w\right)$

$$
-\bar{\rho} \sqrt{\operatorname{Var}\left(x^{i}\right) \bar{\sigma}_{w}^{2}} \leq d_{i} \leq \bar{\rho} \sqrt{\operatorname{Var}\left(x^{i}\right) \bar{\sigma}_{w}^{2}}
$$

and

$$
\sqrt{D^{\prime} \tilde{A} D} \leq \sqrt{\bar{\sigma}_{w}^{2}-k}
$$

where the latter elliptic constraint can be approximated by a polyhedron following BenTal and Nemirovski (2001). Once the constraint is represented by a polyhedron, we may elicit the vertices of the polyhedron by the double description method (Motzkin et al., 1953).

## 4. CONCLUSION

In this study, we propose the partial identification for the linear long regression coefficients from short regression coefficients by aggregating multiple sources. Specifically, we consider two studies that share the same outcome $y$ but contain different key variables $x_{1}$ and $x_{2}$ separately. Our target parameter is the long regression coefficients $E\left[y \mid x_{1}, x_{2}\right]$ but we observe the short regressions $E\left[y \mid x_{1}\right]$ and $E\left[y \mid x_{2}\right]$ only.

We show that the target parameter is point identified when the covariance of $x_{1}$
and $x_{2}$ are known and the long regression regresses only on the variables that are observed in either of two study samples. Oftentimes, the covariance of $x_{1}$ and $x_{2}$ are unknown. Hence, we propose bounds for the target parameter by specifying the worstcase correlation coefficients.

Furthermore, we show that the target parameter is only partially identified when the covariance of $x_{1}$ and $x_{2}$ are known but the long regression contains an omitted variable that is never observed in two study samples. Specifically, we show that an elliptic constraint is critical for the partial identification. The elliptic constraint arises from the constraint on the explained variation of the long regression. We demonstrate that the data combination tightens the bounds as the bounds are constructed as the intersection bounds of each study.

There are a few problems left unresolved. First, the optimization of the objective function for relatively many omitted variables can be challenging. There are a few non-convex optimization problems proposed including the DC algorithm (Le Thi and Pham Dinh, 2018), but we avoid these optimization procedures by focusing on a lowdimensional problem that is typically concerned in Economics studies. Second, we focus on the restrictions up to second moments for the partial identification and exclude other higher-order moments and distributional information. It is possible that this information tightens the bounds. Nevertheless, we limit our focus on the linear projection and the first and second moments because they are relatively accessible than other higher-order moments. Third, we assume that the short regressions represent the same population as the long regression of interest. Considering data combinations from different populations complicates the analysis, and we defer the analysis for future research.

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## APPENDIX A: PROOFS

Proof of Lemma 2.1:

$$
W=\left[\begin{array}{ccc}
A & B & C \\
B^{\prime} & R_{11} & R_{12} \\
C^{\prime} & R_{12}^{\prime} & R_{22}
\end{array}\right]
$$

If $W$ is positive definite, then there is an upper triangular matrix

$$
M=\left[\begin{array}{ccc}
M_{1} & M_{2} & M_{3} \\
0 & M_{4} & M_{5} \\
0 & 0 & M_{6}
\end{array}\right]
$$

such that

$$
W=M^{\prime} M
$$

Note that

$$
\left[\begin{array}{ccc}
M_{1}^{\prime} & 0 & 0 \\
M_{2}^{\prime} & M_{4}^{\prime} & 0 \\
M_{3}^{\prime} & M_{5}^{\prime} & M_{6}^{\prime}
\end{array}\right]\left[\begin{array}{ccc}
M_{1} & M_{2} & M_{3} \\
0 & M_{4} & M_{5} \\
0 & 0 & M_{6}
\end{array}\right]=\left[\begin{array}{ccc}
M_{1}^{\prime} M_{1} & M_{1}^{\prime} M_{2} & M_{1}^{\prime} M_{3} \\
M_{2}^{\prime} M_{1} & M_{2}^{\prime} M_{2}+M_{4}^{\prime} M_{4} & M_{2}^{\prime} M_{3}+M_{4}^{\prime} M_{5} \\
M_{3}^{\prime} M_{1} & M_{3}^{\prime} M_{2}+M_{5}^{\prime} M_{4} & M_{3}^{\prime} M_{3}+M_{5}^{\prime} M_{5}+M_{6}^{\prime} M_{6} .
\end{array}\right]
$$

or

$$
W=\left[\begin{array}{ccc}
A & B & M_{1}^{\prime} M_{3} \\
B^{\prime} & R_{11} & R_{12} \\
M_{3}^{\prime} M_{1} & R_{12}^{\prime} & R_{22}
\end{array}\right]
$$

where $M_{1}$ is known as Cholesky decomposition of $A$ matrix: $A=M_{1}^{\prime} M_{1}$. Consequently,
$M_{3}$ is the only free parameter to optimize and the elements of $C$ maps the elements of $M_{3}$ uniquely given the other parts of the matrix $W$. Let $m_{3}=\operatorname{vec}\left(M_{3}\right)$ with its length $K$. For each element $m_{3 j}$ of $m_{3}$, the derivative of $c^{\prime} W^{-1} c$ is

$$
\frac{\partial c^{\prime} W^{-1} c}{\partial m_{3 j}}=-c^{\prime} W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} M_{3 j} \\
0 & 0 & 0 \\
M_{3 j}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1} c
$$

where $M_{3 j}$ is the matrix $M_{3}$ replacing $m_{3 j}$ element with 1 and all the other with 0 . The cross-derivative with $m_{3 j}$ and $m_{3 i}$ is

$$
\begin{aligned}
\frac{\partial^{2} c^{\prime} W^{-1} c}{\partial m_{3 j} \partial m_{3 i}}= & c^{\prime} W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} M_{3 i} \\
0 & 0 & 0 \\
M_{3 i}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} M_{3 j} \\
0 & 0 & 0 \\
M_{3 j}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1} c \\
& +c^{\prime} W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} M_{3 j} \\
0 & 0 & 0 \\
M_{3 j}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} M_{3 i} \\
0 & 0 & 0 \\
M_{3 i}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1} c .
\end{aligned}
$$

Let $H$ be the Hessian matrix of $c^{\prime} W^{-1} c$ with respect to $m_{3}$. For any non-zero vector $\tilde{c}$ of length $K$,
$\tilde{c}^{\prime} H \tilde{c}=\sum_{i=1}^{K} \sum_{j=1}^{K} \tilde{c}_{i} \tilde{c}_{j} \frac{\partial^{2} c^{\prime} W^{-1} c}{\partial m_{3 j} \partial m_{3 i}}=2 c^{\prime} W^{-1}\left[\begin{array}{ccc}0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\ 0 & 0 & 0 \\ \tilde{M}_{3}^{\prime} M_{1} & 0 & 0\end{array}\right] W^{-1}\left[\begin{array}{ccc}0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\ 0 & 0 & 0 \\ \tilde{M}_{3}^{\prime} M_{1} & 0 & 0\end{array}\right] W^{-1} c$
where $\tilde{M}_{3}=\sum_{i=1}^{K} \tilde{c}_{i} M_{3 i}$. Consequently, the matrix

$$
W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\
0 & 0 & 0 \\
\tilde{M}_{3}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\
0 & 0 & 0 \\
\tilde{M}_{3}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1}
$$

is symmetric and has the Cholesky decomposition of

$$
\left[W^{-1}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\
0 & 0 & 0 \\
\tilde{M}_{3}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1 / 2}\right]\left[W^{-1 / 2}\left[\begin{array}{ccc}
0 & 0 & M_{1}^{\prime} \tilde{M}_{3} \\
0 & 0 & 0 \\
\tilde{M}_{3}^{\prime} M_{1} & 0 & 0
\end{array}\right] W^{-1}\right]
$$

from the positive-definiteness of $W$. This proves that $\tilde{c}^{\prime} H \tilde{c} \geq 0$; hence, $c^{\prime} W^{-1} c$ is a (weakly) convex function with respect to the elements of $C$.
Q.E.D.

Proof of Lemma 3.2: Consider taking derivatives with respect to $D=\left\{d_{1}, \ldots, d_{\bar{L}}\right\}$ and $k$. For each $i \in\{1, \ldots, \bar{D}\}$,

$$
\frac{\partial h}{\partial d_{i}}=c^{\prime}\left[\begin{array}{cc}
A^{-1}\left(D_{i} D^{\prime}+D D_{i}^{\prime}\right) A^{-1} / k & -A^{-1} D_{i} / k \\
-D_{i}^{\prime} A^{-1} / k & 0
\end{array}\right] c .
$$

where $D_{i}$ is a $(\bar{L} \times 1)$ vector with $i$ th element being 1 and 0 otherwise, and

$$
\frac{\partial h}{\partial k}=c^{\prime}\left[\begin{array}{cc}
-A^{-1} D D^{\prime} / k^{2} & A^{-1} D / k^{2} \\
D^{\prime} A^{-1} / k^{2} & -1 / k^{2}
\end{array}\right] c
$$

Taking second derivatives, we obtain

$$
\begin{aligned}
& \frac{\partial^{2} h}{\partial d_{i} \partial d_{j}}=c^{\prime}\left[\begin{array}{cc}
A^{-1}\left(D_{i} D_{j}^{\prime}+D_{j} D_{i}^{\prime}\right) A^{-1} / k & 0 \\
0 & 0
\end{array}\right] c, \\
& \frac{\partial^{2} h}{\partial d_{i} \partial k}=c^{\prime}\left[\begin{array}{cc}
-A^{-1}\left(D_{i} D^{\prime}+D D_{i}^{\prime}\right) A^{-1} / k^{2} & A^{-1} D_{i} / k^{2} \\
D_{i}^{\prime} A^{-1} / k^{2} & 0
\end{array}\right] c,
\end{aligned}
$$

and

$$
\frac{\partial^{2} h}{\partial k^{2}}=c^{\prime}\left[\begin{array}{cc}
2 A^{-1} D D^{\prime} A^{-1} / k^{3} & -2 A^{-1} D / k^{3} \\
-2 D^{\prime} A^{-1} / k^{3} & 2 / k^{3}
\end{array}\right] c
$$

To check the definiteness of the Hessian, $\nabla^{2} h$, take a quadratic form with an arbitrary
non-zero vector $\tilde{y}$ of the same shape as $y$,

$$
\begin{aligned}
& \tilde{y}^{\prime} \nabla^{2} h \tilde{y}=\sum_{i} \sum_{j} \tilde{d}_{i} \tilde{d}_{j} \frac{\partial^{2} h}{\partial d_{i} \partial d_{j}}+\tilde{k}^{2} \frac{\partial^{2} h}{\partial k^{2}}+2 \sum_{i} \tilde{d}_{i} \tilde{k} \frac{\partial^{2} h}{\partial d_{i} \partial k} \\
& =2 c^{\prime}\left[\begin{array}{cc}
A^{-1}\left(k^{-1}\left(\tilde{D} \tilde{D}^{\prime}\right)-\tilde{k} k^{-2}\left(\tilde{D} D^{\prime}+D \tilde{D}^{\prime}\right)+\tilde{k}^{2} k^{-3}\left(D D^{\prime}\right)\right) A^{-1} & A^{-1}\left(\tilde{D} \tilde{k} / k^{2}-D \tilde{k}^{2} / k^{3}\right) \\
\left(\tilde{D}^{\prime} \tilde{k} / k^{2}-D^{\prime} \tilde{k}^{2} / k^{3}\right) A^{-1} & \tilde{k}^{2} / k^{3}
\end{array}\right] c \\
& =2 c^{\prime}\left[\begin{array}{cc}
A^{-1} k^{-1}\left(\left(\tilde{D} \tilde{D}^{\prime}\right)-\tilde{k} k^{-1}\left(\tilde{D} D^{\prime}+D \tilde{D}^{\prime}\right)+\tilde{k}^{2} k^{-2}\left(D D^{\prime}\right)\right) A^{-1} & A^{-1} k^{-1}(\tilde{k} / k)(\tilde{D}-D \tilde{k} / k) \\
k^{-1}(\tilde{k} / k)\left(\tilde{D}^{\prime}-D^{\prime} \tilde{k} / k\right) A^{-1} & k^{-1}(\tilde{k} / k)^{2}
\end{array}\right] c \\
& =2 c^{\prime}\left[\begin{array}{cc}
A^{-1} k^{-1}\left(\tilde{D}-\tilde{k} k^{-1} D\right)\left(\tilde{D}^{\prime}-\tilde{k} k^{-1} D^{\prime}\right) A^{-1} & A^{-1} k^{-1}(\tilde{k} / k)(\tilde{D}-D \tilde{k} / k) \\
k^{-1}(\tilde{k} / k)\left(\tilde{D}^{\prime}-D^{\prime} \tilde{k} / k\right) A^{-1} & k^{-1}(\tilde{k} / k)^{2}
\end{array}\right] c \\
& =2 c^{\prime}\left[\begin{array}{cc}
k^{-1 / 2} A^{-1}\left(\tilde{D}-\tilde{k} k^{-1} D\right) & 0 \\
k^{-1 / 2}(\tilde{k} / k) & 0
\end{array}\right]\left[\begin{array}{cc}
k^{-1 / 2}\left(\tilde{D}^{\prime}-\tilde{k} k^{-1} D^{\prime}\right) A^{-1} & k^{-1 / 2}(\tilde{k} / k) \\
0 & 0
\end{array}\right] c \geq 0 .
\end{aligned}
$$

because the matrix inside is Cholesky decomposed and therefore is positive semidefinite. Consequently, the Hessian matrix is positive semi-definite.
Q.E.D.


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